GOVERNMENT OF INDIA (Ministry of Home Affairs) COMMUNICATION & IT DIRECTORATE CENTRAL RESERVE POLICE FORCE EAST BLOCK-7, SEC-1, R.K. PURAM, NEW DELHI-110066

(Email:- comncell@crpf.gov.in)

No. B.V-7/2024-25-C-(M/UAV)-Q

Dated, the June'2025

To

- 1. The DsG: AR, BSF, CISF, ITBP, NSG, SSB and BPR&D
- 2. Director, DCPW

No. B.V-7/2024-25-C-(M/UAV)-Q

Subject: QRs/TDs OF "MICRO UAV" REGARDING.

I am directed to refer on the subject mentioned above and to say that the QRs/TDs of "Micro UAV" have been approved by the DG CRPF after due deliberations and recommended by CAPFs sub-group and experts from DCPW.

This is for favour of information and needful action please.

Encl:-As above

(Megh Raj)

DIG (Equipment)

Communication & IT Branch
Directorate General C R P F

Dated, the June'2025

Copy to:-

1. Mrs. Sugandhi, Technical Director, North block, MHA with request to upload the QRs/TDs of "Micro UAV" on MHA website (e-mail ID: mpsugandhi@nic.in).

Encl:-As above

(Megh Raj)

DIG (Equipment)

Communication & IT Branch
Directorate General C R P F

QRs/TDs OF MICRO UAV

SN	Parameter	Specifications	Trial Directives
1.	Micro UAV system	ub-systems: -	
1.1	UAV Bird with batte	ry pack	Board will check practically
1.2	Ground Control stat	ion with data link equipment	Board will check practically
1.3	One Payload assemble a) Day Camera only b) Night Camera onle c) Day & Night camed) Integrated day and (as per user requires	y. era payload (both) d night camera	Board will check practically
	Optional for Trainin		
1.4		narger with Power Supply System	Board will check practically
2.	Micro UAV charact		
2.1	Role	Surveillance, reconnaissance, DRI	Board will check practically
2.2	Recovery mode (In meter)	i) Vertical Take Off and Landing (VTOL) from within an area of 5m x 5m clearing or less.	Board will check practically
2.3	Aural Signature (In dB)	≤40dBs at 200 meters Above Ground Level	The firm will submit certificate of Govt Lab or DRDO or NABL or ILAC accredited laboratory.
2.4	Payloads carrying capability	Should have capability to carry electro Optic (EO) for day and Thermal Imager (TI) for night one at a time. or Integrated day & Night payload. (As per user requirement)	Board will check practically
2.5	Flight Modes	a) Fully Autonomous Vertical Take Off b) Fully Autonomous Vertical	Board will check practically Board will check practically
		c) Hover at defined waypoint d) Autonomous waypoint navigation (pre-defined as well as dynamically adjustable waypoints during flight) e) Remote Piloted mode for video-based user navigation. f) Vision based Autonomous Target Tracking of fixed and moving targets. g) Should be controllable in real time from the GCS up to recovery. h) Fully autonomous and stabilize	

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SN	Parameter	Specifications	Trial directives
2.6	Endurance (In Minutes)	a) 40 minutes or more with all payloads at MSL. Reduction in endurance of 10% for every increase of 1000M AMSL. b) Minimum 30 Minutes with payload at 1000M for training UAV (As per user requirement)	Board will check practically with maximum payload up to launch altitude of 1000 meter above mean sea level
2.7	Max. Operating Altitude (In meter)	500M AGL (Above Ground Level) or more.	Board will check practically
2.8	Launch Altitude (In meter)	3000m AMSL (Above Mean Sea Level) or more (As per user requirement)	Board will check practically
2.9	Range of Operation (In KM)	a) Minimum 5 km line of sight b) Minimum 02 KM line of sight for training UAV (As per User Requirement)	Board will check practically
2.10	Cruise Speed (In km/h)	40 km/h or more	Board will check practically and firm will submit OEM certificate.
2.11	Operating Wind Conditions (In km/h)	a) Take off: 30 km/h or more b) Landing: 30 km/h or more c) Operate: 30 km/h or more	Firm will submit OEM Certificate.
2.12	Failsafe features	a) Automatic Return to Home on communication failureb) Automatic Return to Home / Land on low battery	Board will check practically
		c) (i) Multiple GNSS on-board for GPS failure redundancy. (ii) (Including NAVIC) As per user requirement.	Firm will submit OEM Certificate
2.13	Propulsion system	Electrical with rechargeable batteries	Board will check practically
3.	Payload characteris	stics:-	
3.1	Payloads required	One Payload assembly consist of	Board will check practically
	•	 a) Day Camera only b) Night Camera only. c) Day & Night camera payload (both) d) Integrated day and night camera (as per user requirement) 	

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SN	Parameter	Specifi	ications	Trial directives
3.2	Payload and Video		should be gimbal	Board will check practically
	Stabilization	stabilized on-boa	ard.	
		b) Video outp	out should be	
			stabilized at all	
		zoom levels.	stabilized at all	
			eo should not be	
		affected by UAV		
3.3	Electro optic (EO)	a) Camera with	360° pan and	Board will check practically
	Daylight Payload	90° tilt control d		and firm will also submit OEM
		b) Resolution:	1920x1080 or	Certificate
		better	0 1 1 7	
		c) Continuous	-	
			re Optical zoom	
		with minimum- maximum- FO\		
		Field). Digital zoo	•	
		l leidj. Digital Zoe	7111. 121 01 111010	
		(As per User Req	uirement)	
3.4	Thermal Imager	a) Thermal Car	nera with 360°	Board will check practically
	(TI) Night Payload	_	0° tilt control	and firm will also submit OEM
		during flight.		Certificate
		,	40 X 480 pixels	
		or better	-4 1	
		c)White/Black H d) Digital Zoom:		
3.5	Target Detection,	Day payload	4X 01 11101E	Board will check practically,
0.0	Recognition,	Day payload		the picture quality for
	Identification	Vehicle Size	Group of 3-4	
		$(4.5 \times 1.5M)$	people	identification.
	Detection	1500M	1200M	Detection - ability to
	Dogganition	1000M	600M	distinguish an object from
	Recognition	1000101	OOOM	back ground.
	Identification	500M	300M	Recognition – ability to classify the object class (Animal,
				Human, Vehicle, Boat etc).
	Night Payload			Identification – ability to
	Detection	500M	250M	described the object in details
	Detection	300M	250W	(Man with weapon, hat,
				uniform/colour of cloths, types
0.5			0.00) 7.77 11 1	/colour of vehicle)
3.6	Night Recovery	,	GCS) LED light	Board will check practically
	Beacon	when operatin Payload	g with Night	
4.	Ground Control Sta		tics:-	<u> </u>
4.1	(a) Semi ruggedized			Firm will submit certificate of
	Or			govt lab or NABL accredited or
	(b) (As per user requ	irement)		ILAC accredited laboratory.
		,		in the decreasing laboratory.

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SN	Parameter	Specifications	Trial directives
4.2	Computing Ha	ardware for option (a)	
	CPU	Processor minimum frequency 2.3 GHz or better	Board will check practically and Firm will also submit
	Storage	Minimum 256 GB	OEM certificate.
	Memory	4GB or more	
	Display	Minimum 7 inch, Resolution	
		1920x1080 or better, sunlight	
		readable screen, anti-glare.	
4.3	Battery Operation	Minimum 2 Hours at peak utilization.	Board will check practically
4.4	Battery Charging time of GCS	Maximum battery charging time 2 hours for up to 90% of battery charge.	Board will check practically
4.5	Data portability	Ports for data transfer to external secondary storage devices	Board will check practically
4.6	Interface	Type C with support for other interfaces via docking station or adaptors for HDMI, USB, Micro USB, 10/100/1000 Ethernet	Board will check practically
4.7	Capability	 a) Transmit control commands to UAV. b) Receive UAV flight and propulsion parameters. c) Receive, display and record real time day and night video from UAV. Data from UAV d) Capability to control UAV while on the move. 	Board will check practically.
4.8	GCS Application Software	a) Geographic Map along with UAV location, UAV trajectory, camera view polygon, waypoints and flight plan. b) Real-time video from the UAV with on-screen display of important parameters like: - i. Coordinate of target ii. Ground altitude of target iii. UAV Position iv. Height of UAV above ground level v. Distance of UAV from GCS vi. Bearing (Azimuth) of UAV from GCS vii. Ground speed of UAV viii. UAV Heading/ True North indication ix. Mission time x. Battery status of UAV	Board will check it practically

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SN	Parameter	Specifications	Trial directives
		c) Geographic map and real-time video	Board will check it practically
		should be displayed at all times	_
		during the flight.	
		d) Geographic map and real-time video	
		views should be resizable and/or	
		switchable to allow user to switch	
		between big map/small video and	
		small map/big video views through a	
		single click/button input.	
		7	
4.9	Map Formats	a) Should have the capability to	Board will check practically.
1.5	map i oimats	integrate geo-referenced raster maps	Board win cheek practically.
		provided in at least one of the	
		commonly used digital map formats	
		(GIF, TIFF, DTED and SRTM etc)	
		or	
		As per user requirement. b) Should be able to work with	
		Google Maps, application should have	
		the capability to download maps	
		automatically after specifying location	
		GPS co-ordinates.	
4.10	Payload	a) Toggle for Selection and switch	Board will check practically.
	Controls	payload. b) Pan/Tilt/Zoom Controls	
		c) Point payload to ground co-	
		ordinate function	
		d) Recording on/off	
4.11	Button based	i. Full Camera Control	Board will check practically.
	/USB Joystick	·	
	Controls	Zoom In/Out	
		Black/White Hot ii. RPV Mode	
		iii. Altitude Control	
4.12	Video	a) Video should be recorded in any	Board will check practically.
		commonly portable video formats	<u>.</u> 5.
		(AVI/MPEG/ MP4 etc)	
		b) Video of the full flight should be	
		recorded	
		c) Should have capability to take	
		image snapshots at any time during flight	
		d) Software should be provided that	
		will facilitate extraction of imagery	
		from the recorded video post flight	
4.13	Pre-flight	Self-test of UAV system, Output:	Board will check practically.
	checks	go/no go	

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SN	Parameter	Specifications	Trial directives
5.	Communication	Link:-	
5.1	Communication link equipment capability Data link	i) Transmit control commands from GCS to UAV ii) Transmit parameter of UAV and payload to GCS iii) Transmit day and night video from UAV to GCS S/C band (2 GHz to 6 GHz) with Minimum 128-bit AEC Encryption	
6. Ge	⊥ eneral System requ		certificate.
6.1		As per drone rule 2021. The weight of complete Micro UAV bird including battery pack & one payload should ≤ 2kg.	Board will check practically.
6.2	Assembly/ Disassembly time (In minutes)	Less than 10 minutes each.	Board will check practically.
6.3	Life of Micro UAV (In landings)	The total technical life of micro UAV should not be less than 1000 landings.	Firm will submit OEM Certificate.
6.4	Ingress protection of UAV	IP 53 or better or as per user requirement.	Firm will submit certificate of Govt. LAB or NABL or ILAC accredited laboratory.
6.5	Environmental Conditions for Operation and Storage	The UAV and associated systems should be certified for operation and storage for following environment conditions. i) Damp Heat: 40 °C ±2 at RH not less than 90% ii) Operating temperature & Storage temp: -10°C to +50 °C ± 10% Tolerance or As per user requirement. iii) Ability to withstand dust, drizzle and humid conditions	Govt. Lab or NABL or ILAC

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SN	Parameter	Specifications	Trial directives
6.6	Portability and	The Micro UAV should be battery	Board will check practically.
	Operation	operated portable, light in weight,	
		compact, for day and night	
		surveillance, capable of being	
		carried and operated by two men.	
		The complete mission-ready kit	
		including UAV, GCS, and battery	
		should weigh less than 4 kg."	
6.7	Battery of AV	The intelligent standard lithium-	Board will check practically and
		based battery pack should have	firm will produce OEM
		the backup of minimum 40	certificate for chemistry of
		minutes.	battery.
6.8	Battery Charger	Suitable universal battery charger	Board will check practically
	of AV battery	to charge the batteries up to 98 %	
		within two hours.	
6.9	Accessories	a) Water proof Back Packs IP66: 1	Board will check physically and
		set	firm will submit certificate of
			Govt. Lab or NABL accredited or
		b) Field Repair kit: 1 No's	ILAC accredited laboratory for
			IP66
		c) Lithium based Battery packs;	
		2No's	
		d) Spare propeller Sets: 2 No's	
		e) Spare Landing Gear sets: 2 No's	
		f) Associated Cables & Mountings: 1set	
		g) Hard transportation boxes: 1set	
		h) User, Technical & Maintenance	
		Manual: 1set	
		i) Log book: 1 set	
7	Miscellaneous re	quirement	
7.1	Total product	05 years or as per user	Firm will submit OEM certificate
	support	requirement.	
7.2	Manufacturer	Should be provided	BOO will check practically and
1.4	Recommended	•	Firm will also submit OEM
	list of Spare		certificate
	(MRLS)		
7.3	Life of UAV	200 charging cycles or 2 years,	Firm will submit OEM certificate
1.3	battery	whichever is earlier.	
			<u> </u>

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SN	Parameter	Specifications	Trial directives
7.4	Warranty	Minimum 02 years or as per user requirement	Firm will submit OEM certificate.
7.5	Space Ground Control System (2 Remote Controllers – Master and Slave Configuration, Telemetry and Display Device) for training UAV (As per user requirement)		BOO will check practically
7.6	Training Simulator with RC option (As per user requirement)		BOO will check practically

Tushar Sharma AC(Exe), CISF Dinesh S.A AC(QR/UAV), CRPF Laljee Ram JAD, DCPW

Bhagath. R AC (Drones/TUC), SSB R.P. Shukla DC, BSF Pramod Karnar Yadav DC, NSG

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